

An intuitive interpretation of the Fourier Transform

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Let's start with a reminder on the dot product, which we will refer to as scalar product. If we take a vector \vec{v} in \mathbb{R}^n , and a reference vector \vec{e} , the scalar product of \vec{v} and \vec{e} , defined as

$$\langle \vec{v}, \vec{e} \rangle = \sum v_i e_i, \quad (1)$$

describes the projection of \vec{v} onto \vec{e} . If we take a set of reference vectors $\{\vec{e}^{(1)} \dots, \vec{e}^{(n)}\}$ forming a base of \mathbb{R}^n , then in that base we have

$$\vec{v} = \left(\langle \vec{v}, \vec{e}^{(1)} \rangle, \dots, \langle \vec{v}, \vec{e}^{(n)} \rangle \right). \quad (2)$$

In other words, aside from its “natural” representation $\vec{v} = (v_1, v_2, \dots, v_n)$, \vec{v} can also be represented in any base by its projection onto the vectors forming that base.

Let's now look at functions. One can see a function as a vector, although the space it lives in is much larger than where regular vectors live¹. Now one important result: given two functions f and g , the operation

$$\langle f, g \rangle = \int_{-\infty}^{+\infty} f(x) \overline{g(x)} dx \quad (3)$$

is a scalar product.² ($\overline{g(x)}$ means complex conjugate.) Therefore, aside from the usual representation of function f through the number it associates to each possible argument x , one can equivalently “describe” f through its projection onto a set of other functions forming a base of the space of functions:

$$f = \{ \langle f, g_\alpha \rangle \dots \} \quad (4)$$

Importantly, a base of the space of functions would not have a finite number of functions, but an infinite (uncountable) one... so it could be represented, for instance, by a function!

¹Essentially, because every number of the real line (or complex plane) is a possible “direction” of the space of functions.

²This indeed appears as the natural extension of the discrete scalar product of regular vectors in Eq. 1, if we consider each x as a component vector component.

With that being said, we only need to know now that: the set of functions $h_\omega(x) = e^{i\omega x}$, for all $\omega \in \mathbb{R}$, forms a base of the space of functions. Therefore, f can be represented by its projection onto each of these functions:

$$f = \{\langle f, e^{i\omega_1 x} \rangle \dots \} \quad (5)$$

And because the ω cover the entire line of reals, and for each ω there is a corresponding value of the scalar product, the set of all projections actually defines a *function* of ω . So in the base of the $e^{i\omega x}$, the functions f can be represented by the set of its projections, which is a new function $\hat{f}(\omega)$ which for every $\omega \in \mathbb{R}$ associates the projection:

$$\int_{-\infty}^{+\infty} f(x) e^{-i\omega x} dx.^3 \quad (6)$$

The function $\hat{f}(\omega)$ is called Fourier Transform of f , and provides a different representation of the same object.

The choice of this specific base of the space of functions, $e^{i\omega x}$, is convenient because it provides a representation of f in terms of sine and cosine waves, which is useful in a lot of situation. This is not, however, the only possible choice for a base of the space of functions. Alternative bases can be used, which can emphasize different features buried in f . For example, the theory of wavelet decomposition uses base functions that localized in space to detect more localized features of f .

³Note the minus sign: $e^{-i\omega x}$ is the complex conjugate of $e^{i\omega x}$